Cubic Spline Interpolation MATH 375, Numerical Analysis

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Given nodes and data $\{(x_0, f(x_0)), (x_1, f(x_1)), \dots, (x_n, f(x_n))\}$ we have interpolated using:

Lagrange (or Hermite) interpolating polynomials of degree n (or 2n + 1), with n + 1 (or 2n + 2) coefficients,

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- the error term can be difficult to construct and estimate.

An alternative is **piecewise** polynomial approximation, but of what degree polynomial?

- ▶ Piecewise linear results are not differentiable at x_i , i = 0, 1, ..., n.
- Piecewise quadratic results are not twice differentiable at x_i , i = 0, 1, ..., n.
- Piecewise cubic!

Cubic Splines

- A cubic polynomial p(x) = a + bx + cx² + dx³ is specified by 4 coefficients.
- ► The cubic spline is twice continuously differentiable.
- The cubic spline has the flexibility to satisfy general types of boundary conditions.
- While the spline may agree with f(x) at the nodes, we cannot guarantee the derivatives of the spline agree with the derivatives of f.

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Cubic Spline Interpolant (1 of 2)

Given a function f(x) defined on [a, b] and a set of nodes

$$a = x_0 < x_1 < x_2 < \cdots < x_n = b$$

a **cubic spline interpolant**, S(x), for f(x) is a piecewise cubic polynomial with components $S_j(x)$ defined on $[x_j, x_{j+1}]$ for j = 0, 1, ..., n - 1.

$$S(x) = \begin{cases} a_0 + b_0(x - x_0) + c_0(x - x_0)^2 + d_0(x - x_0)^3 & \text{if } x_0 \le x \le x_1 \\ a_1 + b_1(x - x_1) + c_1(x - x_1)^2 + d_1(x - x_1)^3 & \text{if } x_1 \le x \le x_2 \\ \vdots & \vdots & \vdots \\ a_i + b_i(x - x_i) + c_i(x - x_i)^2 + d_i(x - x_i)^3 & \text{if } x_i \le x \le x_{i+1} \\ \vdots & \vdots & \vdots \\ a_{n-1} + b_{n-1}(x - x_{n-1}) + c_{n-1}(x - x_{n-1})^2 + d_{n-1}(x - x_{n-1})^3 & \text{if } x_{n-1} \le x \le x_n \end{cases}$$

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Cubic Spline Interpolant (2 of 2)

The cubic spline interpolant will have the following properties.

•
$$S''(x_0) = S''(x_n) = 0$$
 (free or natural BCs).

• $S'(x_0) = f'(x_0)$ and $S'(x_n) = f'(x_n)$ (clamped BCs).

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Example (1 of 7)

Construct a piecewise cubic spline interpolant for the curve passing through

 $\{(5,5),\,(7,2),\,(9,4)\},$

with natural boundary conditions.



Example (2 of 7)

This will require two cubics:

$$S_0(x) = a_0 + b_0(x-5) + c_0(x-5)^2 + d_0(x-5)^3$$

$$S_1(x) = a_1 + b_1(x-7) + c_1(x-7)^2 + d_1(x-7)^3$$

Since there are 8 coefficients, we must derive 8 equations to solve.

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Example (2 of 7)

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Since there are 8 coefficients, we must derive 8 equations to solve.

The splines must agree with the function (the *y*-coordinates) at the nodes (the *x*-coordinates).

$$5 = S_0(5) = a_0$$

$$2 = S_0(7) = a_0 + 2b_0 + 4c_0 + 8d_0$$

$$2 = S_1(7) = a_1$$

$$4 = S_1(9) = a_1 + 2b_1 + 4c_1 + 8d_1$$

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Example (3 of 7)

The first and second derivatives of the cubics must agree at their shared node x = 7.

$$S'_0(7) = b_0 + 4c_0 + 12d_0 = b_1 = S'_1(7)$$

$$S''_0(7) = 2c_0 + 12d_0 = 2c_1 = S''_1(7)$$

Example (3 of 7)

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 $S''_0(7) = 2c_0 + 12d_0 = 2c_1 = S''_1(7)$

The final two equations come from the natural boundary conditions.

$$S_0''(5) = 0 = 2c_0$$

 $S_1''(9) = 0 = 2c_1 + 12d_1$

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Example (4 of 7)

All eight linear equations together form the system:

$$5 = a_0$$

$$2 = a_0 + 2b_0 + 4c_0 + 8d_0$$

$$2 = a_1$$

$$4 = a_1 + 2b_1 + 4c_1 + 8d_1$$

$$0 = b_0 + 4c_0 + 12d_0 - b_1$$

$$0 = 2c_0 + 12d_0 - 2c_1$$

$$0 = 2c_0$$

$$0 = 2c_1 + 12d_1$$

Example (5 of 7)

The solution is:

i	ai	bi	Ci	di
0	5	$-\frac{17}{8}$	0	$\frac{5}{32}$
1	2	$-\frac{1}{4}$	15 16	$-\frac{5}{32}$

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Example (6 of 7)

The natural cubic spline can be expressed as:

$$S(x) = \begin{cases} 5 - \frac{17}{8}(x-5) + \frac{5}{32}(x-5)^3 & \text{if } 5 \le x \le 7\\ 2 - \frac{1}{4}(x-7) + \frac{15}{16}(x-7)^2 - \frac{5}{32}(x-7)^3 & \text{if } 7 \le x \le 9 \end{cases}$$

Example (7 of 7)

We can verify the continuity of the first and second derivatives from the following graphs.



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General Construction Process

Given n + 1 nodal/data values: { $(x_0, f(x_0)), (x_1, f(x_1)), \dots, (x_n, f(x_n))$ } we will create *n* cubic polynomials.

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General Construction Process

Given n + 1 nodal/data values: { $(x_0, f(x_0)), (x_1, f(x_1)), \dots, (x_n, f(x_n))$ } we will create *n* cubic polynomials.

For j = 0, 1, ..., n - 1 assume

$$S_j(x) = a_j + b_j(x - x_j) + c_j(x - x_j)^2 + d_j(x - x_j)^3.$$

We must find a_j , b_j , c_j and d_j (a total of 4n unknowns) subject to the conditions specified in the definition.

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First Set of Equations

Let
$$h_j = x_{j+1} - x_j$$
 then
 $S_j(x_j) = a_j = f(x_j)$
 $S_{j+1}(x_{j+1}) = a_{j+1} = S_j(x_{j+1}) = a_j + b_j h_j + c_j h_j^2 + d_j h_j^3.$

So far we know a_j for j = 0, 1, ..., n-1 and have n equations and 3n unknowns.

$$a_{1} = a_{0} + b_{0}h_{0} + c_{0}h_{0}^{2} + d_{0}h_{0}^{3}$$

$$\vdots$$

$$a_{j+1} = a_{j} + b_{j}h_{j} + c_{j}h_{j}^{2} + d_{j}h_{j}^{3}$$

$$\vdots$$

$$a_{n} = a_{n-1} + b_{n-1}h_{n-1} + c_{n-1}h_{n-1}^{2} + d_{n-1}h_{n-1}^{3}$$

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First Derivative

The continuity of the first derivative at the nodal points produces *n* more equations.

For $j=0,1,\ldots,n-1$ we have $S_j'(x)=b_j+2c_j(x-x_j)+3d_j(x-x_j)^2.$ Thus

$$egin{aligned} S_j'(x_j) &= b_j \ S_{j+1}'(x_{j+1}) &= b_{j+1} = S_j'(x_{j+1}) = b_j + 2c_jh_j + 3d_jh_j^2 \end{aligned}$$

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Now we have 2*n* equations and 3*n* unknowns.

Equations Derived So Far

$$a_{1} = a_{0} + b_{0}h_{0} + c_{0}h_{0}^{2} + d_{0}h_{0}^{3}$$

$$\vdots$$

$$a_{j+1} = a_{j} + b_{j}h_{j} + c_{j}h_{j}^{2} + d_{j}h_{j}^{3}$$

$$\vdots$$

$$a_{n} = a_{n-1} + b_{n-1}h_{n-1} + c_{n-1}h_{n-1}^{2} + d_{n-1}h_{n-1}^{3}$$

$$b_{1} = b_{0} + 2c_{0}h_{0} + 3d_{0}h_{0}^{2}$$

$$\vdots$$

$$b_{j+1} = b_{j} + 2c_{j}h_{j} + 3d_{j}h_{j}^{2}$$

$$\vdots$$

$$b_{n} = b_{n-1} + 2c_{n-1}h_{n-1} + 3d_{n-1}h_{n-1}^{2}$$

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The unknowns are b_j , c_j , and d_j for j = 0, 1, ..., n - 1.

Second Derivative

The continuity of the second derivative at the nodal points produces *n* more equations.

For $j=0,1,\ldots,n-1$ we have $S_j^{\prime\prime}(x)=2c_j+6d_j(x-x_j).$ Thus $S_i^{\prime\prime}(x_j)=2c_j$

$$S_{j+1}''(x_{j+1}) = 2c_{j+1} = S_j''(x_{j+1}) = 2c_j + 6d_jh_j$$

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Now we have 3*n* equations and 3*n* unknowns.

Equations Derived So Far

$$a_{j+1} = a_j + b_j h_j + c_j h_j^2 + d_j h_j^3 \text{ (for } j = 0, 1, ..., n-1\text{)}$$

$$b_{j+1} = b_j + 2c_j h_j + 3d_j h_j^2 \text{ (for } j = 0, 1, ..., n-1\text{)}$$

$$2c_1 = 2c_0 + 6d_0 h_0$$

$$\vdots$$

$$2c_{j+1} = 2c_j + 6d_j h_j$$

$$\vdots$$

$$2c_n = 2c_{n-1} + 6d_{n-1} h_{n-1}$$

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The unknowns are b_j , c_j , and d_j for $j = 0, 1, \ldots, n-1$.

Summary of Equations

For j = 0, 1, ..., n - 1 we have

$$a_{j+1} = a_j + b_j h_j + c_j h_j^2 + d_j h_j^3$$

 $b_{j+1} = b_j + 2c_j h_j + 3d_j h_j^2$
 $c_{j+1} = c_j + 3d_j h_j.$

Note: The quantities a_j and h_j are known.

Summary of Equations

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 $b_{j+1} = b_j + 2c_j h_j + 3d_j h_j^2$
 $c_{j+1} = c_j + 3d_j h_j.$

Note: The quantities a_j and h_j are known. Solve the third equation for d_j and substitute into the other two equations.

$$d_j = rac{c_{j+1}-c_j}{3h_j}$$

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This eliminates *n* equations of the third type.

$$a_{j+1} = a_j + b_j h_j + c_j h_j^2 + d_j h_j^3$$

$$egin{aligned} a_{j+1} &= a_j + b_j h_j + c_j h_j^2 + d_j h_j^3 \ &= a_j + b_j h_j + c_j h_j^2 + \left(rac{c_{j+1} - c_j}{3h_j}
ight) h_j^3 \ &= a_j + b_j h_j + rac{h_j^2}{3}(2c_j + c_{j+1}) \end{aligned}$$

$$\begin{aligned} a_{j+1} &= a_j + b_j h_j + c_j h_j^2 + d_j h_j^3 \\ &= a_j + b_j h_j + c_j h_j^2 + \left(\frac{c_{j+1} - c_j}{3h_j}\right) h_j^3 \\ &= a_j + b_j h_j + \frac{h_j^2}{3} (2c_j + c_{j+1}) \\ b_{j+1} &= b_j + 2c_j h_j + 3d_j h_j^2 \end{aligned}$$

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$$\begin{aligned} a_{j+1} &= a_j + b_j h_j + c_j h_j^2 + d_j h_j^3 \\ &= a_j + b_j h_j + c_j h_j^2 + \left(\frac{c_{j+1} - c_j}{3h_j}\right) h_j^3 \\ &= a_j + b_j h_j + \frac{h_j^2}{3} (2c_j + c_{j+1}) \\ b_{j+1} &= b_j + 2c_j h_j + 3d_j h_j^2 \\ &= b_j + 2c_j h_j + 3\left(\frac{c_{j+1} - c_j}{3h_j}\right) h_j^2 \\ &= b_j + h_j (c_j + c_{j+1}) \end{aligned}$$

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$$\begin{aligned} a_{j+1} &= a_j + b_j h_j + c_j h_j^2 + d_j h_j^3 \\ &= a_j + b_j h_j + c_j h_j^2 + \left(\frac{c_{j+1} - c_j}{3h_j}\right) h_j^3 \\ &= a_j + b_j h_j + \frac{h_j^2}{3} (2c_j + c_{j+1}) \\ b_{j+1} &= b_j + 2c_j h_j + 3d_j h_j^2 \\ &= b_j + 2c_j h_j + 3\left(\frac{c_{j+1} - c_j}{3h_j}\right) h_j^2 \\ &= b_j + h_j (c_j + c_{j+1}) \end{aligned}$$

Solve the first equation for b_i .

$$b_j = rac{1}{h_j}(a_{j+1} - a_j) - rac{h_j}{3}(2c_j + c_{j+1})$$

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We have for j = 0, 1, ..., n - 1,

$$b_j = rac{1}{h_j}(a_{j+1} - a_j) - rac{h_j}{3}(2c_j + c_{j+1}).$$

Replace index *j* by j - 1 to obtain

$$b_{j-1} = \frac{1}{h_{j-1}}(a_j - a_{j-1}) - \frac{h_{j-1}}{3}(2c_{j-1} + c_j).$$

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for j = 1, 2, ..., n.

We have for j = 0, 1, ..., n - 1,

$$b_j = rac{1}{h_j}(a_{j+1} - a_j) - rac{h_j}{3}(2c_j + c_{j+1}).$$

Replace index *j* by j - 1 to obtain

$$b_{j-1} = \frac{1}{h_{j-1}}(a_j - a_{j-1}) - \frac{h_{j-1}}{3}(2c_{j-1} + c_j).$$

for j = 1, 2, ..., n.

We can also re-index the earlier equation

$$b_{j+1} = b_j + h_j(c_j + c_{j+1})$$

to obtain

$$b_j = b_{j-1} + h_{j-1}(c_{j-1} + c_j).$$

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$$b_j = b_{j-1} + h_{j-1}(c_{j-1} + c_j).$$

Substitute the equations for b_{j-1} and b_j into the equation above. This step eliminates *n* equations of the first type.

$$egin{aligned} &rac{1}{h_j}(a_{j+1}-a_j)-rac{h_j}{3}(2c_j+c_{j+1})\ &=rac{1}{h_{j-1}}(a_j-a_{j-1})-rac{h_{j-1}}{3}(2c_{j-1}+c_j)+h_{j-1}(c_{j-1}+c_j) \end{aligned}$$

Collect all terms involving c_k to one side.

$$h_{j-1}c_{j-1} + 2c_j(h_{j-1} + h_j) + h_jc_{j+1} = \frac{3}{h_j}(a_{j+1} - a_j) - \frac{3}{h_{j-1}}(a_j - a_{j-1})$$

or $j = 1, 2, \dots, n-1$.

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$$b_j = b_{j-1} + h_{j-1}(c_{j-1} + c_j).$$

Substitute the equations for b_{j-1} and b_j into the equation above. This step eliminates *n* equations of the first type.

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Collect all terms involving c_k to one side.

$$h_{j-1}c_{j-1} + 2c_j(h_{j-1} + h_j) + h_jc_{j+1} = \frac{3}{h_j}(a_{j+1} - a_j) - \frac{3}{h_{j-1}}(a_j - a_{j-1})$$

for $j = 1, 2, \ldots, n - 1$.

Remark: we have n - 1 equations and n + 1 unknowns.

Natural Boundary Conditions

If
$$S''(x_0) = S''_0(x_0) = 2c_0 = 0$$
 then $c_0 = 0$ and if $S''(x_n) = S''_{n-1}(x_n) = 2c_n = 0$ then $c_n = 0$.

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Natural Boundary Conditions

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 then $c_0 = 0$ and if $S''(x_n) = S''_{n-1}(x_n) = 2c_n = 0$ then $c_n = 0$.

Theorem

If *f* is defined at $a = x_0 < x_1 < \cdots < x_n = b$ then *f* has a unique natural cubic spline interpolant.

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Natural BC Linear System (1 of 3)

In matrix form the system of n + 1 equations has the form Ac = y where

$$A = \begin{bmatrix} 1 & 0 & 0 & 0 & \cdots & 0 \\ h_0 & 2(h_0 + h_1) & h_1 & 0 & \cdots & 0 \\ 0 & h_1 & 2(h_1 + h_2) & h_2 & \cdots & 0 \\ \vdots & \vdots & \vdots & \vdots & \vdots \\ 0 & 0 & 0 & h_{n-2} & 2(h_{n-2} + h_{n-1}) & h_{n-1} \\ 0 & 0 & 0 & 0 & \cdots & 1 \end{bmatrix}$$

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Note: *A* is a tridiagonal matrix.

Natural BC Linear System (2 of 3)

The vector **y** on the right-hand side is formed as

$$\mathbf{y} = \begin{bmatrix} 0 \\ \frac{3}{h_{1}}(a_{2} - a_{1}) - \frac{3}{h_{0}}(a_{1} - a_{0}) \\ \frac{3}{h_{2}}(a_{3} - a_{2}) - \frac{3}{h_{1}}(a_{2} - a_{1}) \\ \vdots \\ \frac{3}{h_{n-2}}(a_{n-1} - a_{n-2}) - \frac{3}{h_{n-3}}(a_{n-2} - a_{n-3}) \\ \frac{3}{h_{n-1}}(a_{n} - a_{n-1}) - \frac{3}{h_{n-2}}(a_{n-1} - a_{n-2}) \\ 0 \end{bmatrix}$$

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Note: *A* is a tridiagonal matrix.

Natural BC Linear System (3 of 3)

$$A\begin{bmatrix} c_{0}\\ c_{1}\\ c_{2}\\ \vdots\\ c_{n-1}\\ c_{n}\end{bmatrix} = \begin{bmatrix} 0\\ \frac{3}{h_{1}}(a_{2}-a_{1})-\frac{3}{h_{0}}(a_{1}-a_{0})\\ \frac{3}{h_{2}}(a_{3}-a_{2})-\frac{3}{h_{1}}(a_{2}-a_{1})\\ \vdots\\ \frac{3}{h_{n-1}}(a_{n}-a_{n-1})-\frac{3}{h_{n-2}}(a_{n-1}-a_{n-2})\\ 0\end{bmatrix}$$

We solve this linear system of equations using a common algorithm for handling tridiagonal systems.

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Natural Cubic Spline Algorithm

INPUT { $(x_0, f(x_0)), (x_1, f(x_1)), \dots, (x_n, f(x_n))$ } STEP 1 For i = 0, 1, ..., n - 1 set $a_i = f(x_i)$; set $h_i = x_{i+1} - x_i$. STEP 2 For i = 1, 2, ..., n - 1 set $\alpha_i = \frac{3}{h_i}(a_{i+1} - a_i) - \frac{3}{h_{i-1}}(a_i - a_{i-1}).$ STEP 3 Set $l_0 = 1$; set $\mu_0 = 0$; set $z_0 = 0$. STEP 4 For i = 1, 2, ..., n-1 set $l_i = 2(x_{i+1} - x_{i-1}) - h_{i-1}\mu_{i-1}$; set $\mu_i = \frac{h_i}{l_i}$; set $z_i = \frac{\alpha_i - h_{i-1}z_{i-1}}{l_i}$. STEP 5 Set $I_n = 1$; set $c_n = 0$; set $z_n = 0$. STEP 6 For j = n - 1, n - 2, ..., 0 set $c_j = z_j - \mu_j c_{j+1}$; set $b_j = rac{a_{j+1} - a_j}{h_i} - rac{h_j(c_{j+1} + 2c_j)}{3}; ext{ set } d_j = rac{c_{j+1} - c_j}{3h_i}.$ STEP 7 For j = 0, 1, ..., n - 1 OUTPUT a_i, b_i, c_i, d_i .

Example (1 of 4)

Construct the natural cubic spline interpolant for $f(x) = \ln(e^x + 2)$ with nodal values:

X	f(x)
-1.0	0.86199480
-0.5	0.95802009
0.0	1.0986123
0.5	1.2943767

Calculate the absolute error in using the interpolant to approximate f(0.25) and f'(0.25).

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Example (2 of 4)

In this case n = 3 and

$$h_0 = h_1 = h_2 = 0.5$$

with

$$a_0 = 0.86199480, a_1 = 0.95802009, a_2 = 1.0986123, a_3 = 1.2943767.$$

The linear system resembles,

$$A\mathbf{c} = \begin{bmatrix} 1.0 & 0.0 & 0.0 & 0.0 \\ 0.5 & 2.0 & 0.5 & 0.0 \\ 0.0 & 0.5 & 2.0 & 0.5 \\ 0.0 & 0.0 & 0.0 & 1.0 \end{bmatrix} \begin{bmatrix} c_0 \\ c_1 \\ c_2 \\ c_3 \end{bmatrix} = \begin{bmatrix} 0.0 \\ 0.267402 \\ 0.331034 \\ 0.0 \end{bmatrix} = \mathbf{y}$$

Example (3 of 4)

The coefficients of the piecewise cubics:

i	ai	bi	Ci	d_i
0	0.861995	0.175638	0.0	0.0656509
1	0.95802	0.224876	0.0984763	0.028281
2	1.09861	0.344563	0.140898	-0.093918

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Example (3 of 4)

The coefficients of the piecewise cubics:

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1	0.95802	0.224876	0.0984763	0.028281
2	1.09861	0.344563	0.140898	-0.093918

The cubic spline:

$$S(x) = \begin{cases} 0.861995 + 0.175638(x+1) & \text{if } -1 \le x \le -0.5 \\ + 0.0656509(x+1)^3 & & \\ 0.95802 + 0.224876(x+0.5) & & \\ + 0.0984763(x+0.5)^2 & & \text{if } -0.5 \le x \le 0 \\ + 0.028281(x+0.5)^3 & & \\ 1.09861 + 0.344563x & & & \text{if } 0 \le x \le 0.5 \\ + 0.140898x^2 - 0.093918x^3 & & \\ \end{cases}$$

Example (4 of 4)



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Clamped Boundary Conditions (1 of 2)

If
$$S'(a)=S_0'(a)=f'(a)=b_0$$
 then $f'(a)=rac{1}{h_0}(a_1-a_0)-rac{h_0}{3}(2c_0+c_1)$

which is equivalent to

$$h_0(2c_0+c_1)=rac{3}{h_0}(a_1-a_0)-3f'(a).$$

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This replaces the first equation in our system of *n* equations.

Clamped Boundary Conditions (2 of 2)

Likewise if $S'(b) = S'_n(b) = f'(b) = b_n$ then

$$b_{n} = b_{n-1} + h_{n-1}(c_{n-1} + c_{n})$$

= $\frac{1}{h_{n-1}}(a_{n} - a_{n-1}) - \frac{h_{n-1}}{3}(2c_{n-1} + c_{n}) + h_{n-1}(c_{n-1} + c_{n})$
= $\frac{1}{h_{n-1}}(a_{n} - a_{n-1}) + \frac{h_{n-1}}{3}(c_{n-1} + 2c_{n})$

which is equivalent to

$$h_{n-1}(c_{n-1}+2c_n)=3f'(b)-rac{3}{h_{n-1}}(a_n-a_{n-1}).$$

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This replaces the last equation in our system of *n* equations.

Clamped BC Linear System (1 of 2)

Theorem

If *f* is defined at $a = x_0 < x_1 < \cdots < x_n = b$ and differentiable at x = a and at x = b, then *f* has a unique clamped cubic spline interpolant. In matrix form the system of *n* equations has the form $A\mathbf{c} = \mathbf{y}$ where

$$A = \begin{bmatrix} 2h_0 & h_0 & 0 & 0 & \cdots & 0 \\ h_0 & 2(h_0 + h_1) & h_1 & 0 & \cdots & 0 \\ 0 & h_1 & 2(h_1 + h_2) & h_2 & \cdots & 0 \\ \vdots & \vdots & \vdots & \vdots & \vdots \\ 0 & 0 & 0 & h_{n-2} & 2(h_{n-2} + h_{n-1}) & h_{n-1} \\ 0 & 0 & 0 & \cdots & h_{n-1} & 2h_{n-1} \end{bmatrix}$$

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Note: A is a tridiagonal matrix.

Clamped BC Linear System (2 of 2)

$$A\begin{bmatrix} C_{0}\\ C_{1}\\ C_{2}\\ \vdots\\ C_{n-2}\\ C_{n-1}\\ C_{n}\end{bmatrix} = \begin{bmatrix} \frac{\frac{3}{h_{0}}(a_{1}-a_{0})-3f'(a)}{\frac{3}{h_{1}}(a_{2}-a_{1})-\frac{3}{h_{0}}(a_{1}-a_{0})}{\frac{3}{h_{2}}(a_{3}-a_{2})-\frac{3}{h_{1}}(a_{2}-a_{1})}\\ \vdots\\ \frac{3}{h_{n-2}}(a_{n-1}-a_{n-2})-\frac{3}{h_{n-3}}(a_{n-2}-a_{n-3})}{\frac{3}{h_{n-1}}(a_{n}-a_{n-1})-\frac{3}{h_{n-2}}(a_{n-1}-a_{n-2})}\\ 3f'(b)-\frac{3}{h_{n-1}}(a_{n}-a_{n-1})\end{bmatrix}$$

Coefficients of the Cubic Splines

Since a_j for j = 0, 1, ..., n is known, once we solve the linear system for c_j (again for j = 0, 1, ..., n) then

$$egin{aligned} b_j &= rac{1}{h_j}(a_{j+1}-a_j) - rac{h_j}{3}(c_{j+1}+2c_j) \ d_j &= rac{1}{3h_j}(c_{j+1}-c_j) \end{aligned}$$

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for j = 0, 1, ..., n - 1.

Clamped Cubic Spline Algorithm (1 of 2)

INPUT {
$$(x_0, f(x_0)), (x_1, f(x_1)), \dots, (x_n, f(x_n))$$
}, $f'(x_0)$, and
 $f'(x_n)$.
STEP 1 For $i = 0, 1, \dots, n-1$ set $a_i = f(x_i)$; set $h_i = x_{i+1} - x_i$.
STEP 2 Set $\alpha_0 = \frac{3(a_1 - a_0)}{h_0} - 3f'(x_0)$;
 $\alpha_n = 3f'(x_n) - \frac{3(a_n - a_{n-1})}{h_{n-1}}$.
STEP 3 For $i = 1, 2, \dots, n-1$ set
 $\alpha_i = \frac{3}{h_i}(a_{i+1} - a_i) - \frac{3}{h_{i-1}}(a_i - a_{i-1})$.
STEP 4 Set $l_0 = 2h_0$; $\mu_0 = 0.5$; $z_0 = \frac{\alpha_0}{l_0}$.

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Clamped Cubic Spline Algorithm (2 of 2)

STEP 5 For
$$i = 1, 2, ..., n - 1$$
 set $l_i = 2(x_{i+1} - x_{i-1}) - h_{i-1}\mu_{i-1};$
 $\mu_i = \frac{h_i}{l_i}; z_i = \frac{\alpha_i - h_{i-1}z_{i-1}}{l_i}.$
STEP 6 Set $l_n = h_{n-1}(2 - \mu_{n-1}); z_n = \frac{\alpha_n - h_{n-1}z_{n-1}}{l_n}; c_n = z_n.$
STEP 7 For $j = n - 1, n - 2, ..., 0$ set $c_j = z_j - \mu_j c_{j+1};$
 $b_j = \frac{a_{j+1} - a_j}{h_j} - \frac{h_j(c_{j+1} + 2c_j)}{3}; d_j = \frac{c_{j+1} - c_j}{3h_j}.$
STEP 8 For $j = 0, 1, ..., n - 1$ OUTPUT $a_j, b_j, c_j, d_j.$

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Example (1 of 4)

Construct the clamped cubic spline interpolant for $f(x) = \ln(e^x + 2)$ with nodal values:

X	f(x)
-1.0	0.86199480
-0.5	0.95802009
0.0	1.0986123
0.5	1.2943767

Calculate the absolute error in using the interpolant to approximate f(0.25) and f'(0.25).

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Example (2 of 4)

In this case n = 3 and

$$h_0 = h_1 = h_2 = 0.5$$

with

$$a_0 = 0.86199480, a_1 = 0.95802009, a_2 = 1.0986123, a_3 = 1.2943767.$$

Note that $f'(-1) \approx 0.155362$ and $f'(0.5) \approx 0.451863$.

The linear system resembles,

$$A\mathbf{c} = \begin{bmatrix} 1.0 & 0.5 & 0.0 & 0.0 \\ 0.5 & 2.0 & 0.5 & 0.0 \\ 0.0 & 0.5 & 2.0 & 0.5 \\ 0.0 & 0.0 & 0.5 & 1.0 \end{bmatrix} \begin{bmatrix} c_0 \\ c_1 \\ c_2 \\ c_3 \end{bmatrix} = \begin{bmatrix} 0.110064 \\ 0.267402 \\ 0.331034 \\ 0.181001 \end{bmatrix} = \mathbf{y}.$$

Example (3 of 4)

The coefficients of the piecewise cubics:

i	ai	bi	Ci	d_i
0	0.861995	0.155362	0.0653748	0.0160031
1	0.95802	0.23274	0.0893795	0.0150207
2	1.09861	0.333384	0.11191	0.00875717

Example (3 of 4)

The coefficients of the piecewise cubics:

i	ai	bi	Ci	d_i
0	0.861995	0.155362	0.0653748	0.0160031
1	0.95802	0.23274	0.0893795	0.0150207
2	1.09861	0.333384	0.11191	0.00875717

The cubic spline:

$$S(x) = \begin{cases} 0.861995 + 0.155362(x+1) \\ + 0.0653748(x+1)^2 & \text{if } -1 \le x \le -0.5 \\ + 0.0160031(x+1)^3 & 0.95802 + 0.23274(x+0.5) \\ + 0.0893795(x+0.5)^2 & \text{if } -0.5 \le x \le 0 \\ + 0.0150207(x+0.5)^3 & 1.09861 + 0.333384x + 0.11191x^2 & \text{if } 0 \le x \le 0.5 \\ + 0.00875717x^3 & \text{if } 0 \le x \le 0.5 \end{cases}$$

Example (4 of 4)



Error Analysis

Theorem Let $f \in C^4[a, b]$ with $\max_{a \le x \le b} |f^{(4)}(x)| = M$. If *S* is the unique clamped cubic spline interpolant to *f* with respect to nodes $a = x_0 < x_1 < \cdots < x_n = b$, then for all $x \in [a, b]$,

$$|f(x) - S(x)| \leq \frac{5M}{384} \max_{0 \leq j \leq n-1} (x_{j+1} - x_j)^4.$$

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Example

Earlier we found the clamped cubic spline interpolant for $f(x) = \ln(e^x + 2)$. In this example $x_{j+1} - x_j = 0.5$ for all *j*. Note that

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Natural Cubic Spline Example (1 of 3)

Consider the following data:

X	f(x)
-0.5	-0.02475
-0.25	0.334938
0.0	1.101

The linear system takes the form

 $A\mathbf{c} = \mathbf{y}$ $\begin{bmatrix} 1.00 & 0.00 & 0.00\\ 0.25 & 1.00 & 0.25\\ 0.00 & 0.00 & 1.00 \end{bmatrix} \begin{bmatrix} c_0\\ c_1\\ c_2 \end{bmatrix} = \begin{bmatrix} 0.00\\ 4.8765\\ 0.00 \end{bmatrix}$

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Natural Cubic Spline Example (2 of 3)

The coefficients of the natural cubic spline interpolant are

a _i	bi	Ci	d_i
-0.02475	1.03238	0.0	6.502
0.334938	2.2515	4.8765	-6.502

and the piecewise cubic is

$$S(x) = \begin{cases} -0.02475 + 1.03238(x+0.5) + 6.502(x+0.05)^3 & \text{if } -0.5 \le x \le -0.25\\ 0.334938 + 2.2515(x+0.25) + 4.8765(x+0.25)^2 - 6.502(x+0.25)^3 & \text{if } -0.25 \le x \le 0. \end{cases}$$

Natural Cubic Spline Example (3 of 3)



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Clamped Cubic Spline Example (1 of 4)

Here we will find the clamped cubic spline interpolant to the function $f(x) = J_0(\sqrt{x})$ at the nodes $x_i = 5i$ for i = 0, 1, ..., 10.

X	f(x)
0.0	1.0
5.0	0.0904053
10.0	-0.310045
÷	:
50.0	0.299655

Note: f'(0) = -0.25 and f'(50) = -0.00117217.

Clamped Cubic Spline Example (2 of 4)

The tridiagonal linear system takes the following form

											0.204243
	_	•			•	•	•	• 7			0.305487
10	5	0	0	•••	0	0	0	0	c_0		0.184846
5	20	5	0	•••	0	0	0	0	C1		0.100749
0	5	20	5	•••	0	0	0	0	<i>C</i> ₂		0.044242
				٠.				:		=	0.008211
0	0	0	0		5	20	5	0	C ₈		-0.012944
0	0	0	0		0	5	20	5			-0.023582
0	0	0	0		0	0	5	10			-0.027056
L	Ũ	5	5		5		5	.5]			-0.025905
											0.011808 _

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Clamped Cubic Spline Example (3 of 4)

The coefficients of the clamped cubic spline interpolant are

ai	b _i	Ci	di
1	-0.25	0.0154655	-0.00036986
0.09040533	-0.1230843	0.009917643	-0.0002637577
-0.3100448	-0.0436897	0.005961278	-0.0001836499
-0.4024176	0.00214934	0.003206529	-0.0001229411
-0.3268753	0.02499404	0.001362412	-0.0000780158
-0.1775968	0.03276697	0.000192174	-0.0000454083
-0.0146336	0.03128308	-0.00048895	-0.0000224102
0.12675676	0.02471281	-0.00082510	$-6.79522 imes 10^{-6}$
0.22884382	0.01595213	-0.00092703	$3.265389 imes 10^{-6}$
0.28583684	0.00692671	-0.00087805	$9.088463 imes 10^{-6}$

Clamped Cubic Spline Example (4 of 4)



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Homework

Read Section 3.5

Exercises: 1, 3d, 5d, 7d, 25