

Introduction to Ordinary Differential Equations

MATH 375 Numerical Analysis

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Background

- ▶ **Ordinary Differential Equations** (ODEs) are mathematical models of quantities and their rates of change with respect to a single independent variable.
- ▶ ODEs have numerous applications in the STEM fields.
- ▶ The independent variable is often time (denoted t) or position (denoted x in Cartesian coordinates and θ) in polar coordinates).
- ▶ ODEs are often derived from well-known laws of motion (particularly Newton's 2nd Law: $\mathbf{F} = m\mathbf{a}$) and **free body diagrams**).

Free Body Diagrams

A free body diagram is an idealized depiction of an object and the forces acting on it. Common forces include:

gravity: acting downward with magnitude $m g$ where m is the mass of the body.

tension/compression: transmitted through ropes, wires, chains, rods, dowels, poles, *etc.*

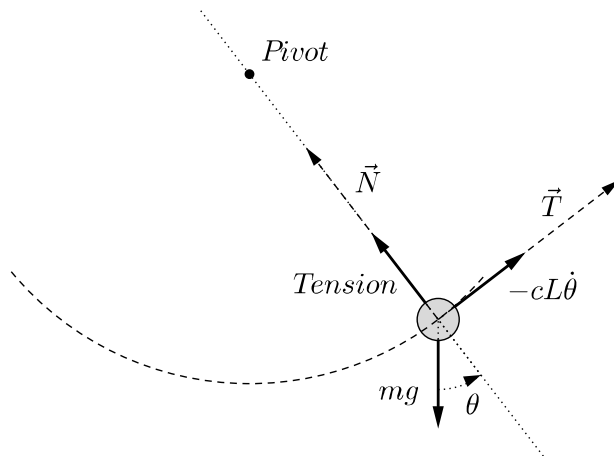
spring: proportional to the amount of deformation, directed opposite the deformation.

normal: perpendicular away from a surface to keep the object from sinking into the surface.

friction: opposing motion with proportionality constant μ (coefficient of friction). Often divided into static and dynamic friction.

applied: by other objects (*e.g.*, people, motors, *etc.*).

Example: Pendulum



Forces on Pendulum

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In the tangential direction, the velocity of the pendulum bob is $L \frac{d\theta}{dt}$, the friction is $-\mu L \frac{d\theta}{dt}$, and the acceleration is $L \frac{d^2\theta}{dt^2}$.

Pendulum ODE

Since the pendulum bob is accelerating only in the tangential direction, then according to Newton's 2nd Law of Motion,

$$m \mathbf{a}_T = -m \mathbf{g} \sin \theta - \mu L \frac{d\theta}{dt}$$

$$m L \frac{d^2\theta}{dt^2} = -m g \sin \theta - \mu L \frac{d\theta}{dt}$$

$$\frac{d^2\theta}{dt^2} + \frac{\mu}{m} \frac{d\theta}{dt} + \frac{g}{L} \sin \theta = 0.$$

- ▶ The unknown is θ .
- ▶ The ODE is described as **second-order** since the highest derivative of the unknown present is $\frac{d^2\theta}{dt^2}$.
- ▶ The ODE is **nonlinear** because of the term $\sin \theta$.

Initial Value Problem

If two side conditions are specified (for instance the initial position $\theta(0)$ and the initial velocity $\theta'(0)$) the system of equations,

$$\begin{aligned}\frac{d^2\theta}{dt^2} + \frac{\mu}{m} \frac{d\theta}{dt} + \frac{g}{L} \sin \theta &= 0 \\ \theta(0) &= \theta_0 \\ \theta'(0) &= \omega_0,\end{aligned}$$

is called an **initial value problem** (IVP).

Example

Show that $\theta(t) = e^{2t}$ is a solution to the ODE:

$$3\frac{d^2\theta}{dt^2} - 8\frac{d\theta}{dt} + 4\theta = 0.$$

Solution

$$\begin{aligned}3\frac{d^2}{dt^2}[e^{2t}] - 8\frac{d}{dt}[e^{2t}] + 4e^{2t} &= 0 \\3(4e^{2t}) - 8(2e^{2t}) + 4e^{2t} &= 0 \\12e^{2t} - 16e^{2t} + 4e^{2t} &= 0 \\0 &= 0\end{aligned}$$

Example

Show that $y(t) = \sqrt{1+t^2}$ is a solution to the IVP:

$$\begin{aligned}\frac{dy}{dt} &= \frac{t}{y} \\ y(0) &= 1.\end{aligned}$$

Solution

We can check $y(0) = \sqrt{1+(0)^2} = \sqrt{1} = 1$, so the initial condition is satisfied.

$$\begin{aligned}\frac{d}{dt} \left[\sqrt{1+t^2} \right] &= \frac{t}{\sqrt{1+t^2}} \\ \frac{t}{\sqrt{1+t^2}} &= \frac{t}{\sqrt{1+t^2}}\end{aligned}$$

Finding Solutions to ODEs

Provided the ODE is of a special form:

- ▶ first or second order,
- ▶ linear,
- ▶ separable, or
- ▶ exact

we can usually find the solution.

The solution technique, **separation of variables**, uses elementary calculus and integration.

Separation of Variables

Consider the general, first-order ODE:

$$\frac{dy}{dt} = f(t, y).$$

If this ODE can be algebraically manipulated into the form:

$$M(t) dt + N(y) dy = 0$$

we say that the ODE is **separable**.

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we say that the ODE is **separable**.

We can separate the independent and dependent variables as

$$N(y) dy = -M(t) dt,$$

and integrate both sides.

Examples

Verify that the following first-order ODEs are separable.

$$\frac{dy}{dt} = \frac{t^2}{y(1+t^3)}$$

$$\frac{dy}{dt} = \frac{y^2}{t}$$

$$\frac{dy}{dt} = \frac{3t^2}{3y^2 - 4}$$

Solution: $\frac{dy}{dt} = \frac{t^2}{y(1+t^3)}$

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$$\frac{1}{2}y^2 = \frac{1}{3} \ln |1+t^3| + C$$

Solution: $\frac{dy}{dt} = \frac{y^2}{t}$

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Solution: $\frac{dy}{dt} = \frac{y^2}{t}$

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$$\int \frac{1}{y^2} dy = \int \frac{1}{t} dt$$

$$-\frac{1}{y} = \ln |t| + C$$

$$y = \frac{-1}{\ln |t| + C}$$

Solution: $\frac{dy}{dt} = \frac{3t^2}{3y^2 - 4}$

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$$\begin{aligned}\frac{dy}{dt} &= \frac{3t^2}{3y^2 - 4} \\ (3y^2 - 4) dy &= 3t^2 dt\end{aligned}$$

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$$y^3 - 4y = t^3 + C$$

Homework

- ▶ Read Section 6.1.
- ▶ Exercises: