

Relaxation Techniques for Solving Linear Systems

MATH 375 Numerical Analysis

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Objectives

In this lesson we will learn to

- ▶ accelerate the convergence of an iterative method for solving a linear system, and
- ▶ select the the iterative method with the most rapid convergence.

Residual Vector

Definition

Suppose vector $\tilde{\mathbf{x}} \in \mathbb{R}^n$ is an approximation to the solution of the linear system $A\mathbf{x} = \mathbf{b}$. The **residual vector** for $\tilde{\mathbf{x}}$ with respect to this system is $\mathbf{r} = \mathbf{b} - A\tilde{\mathbf{x}}$.

Residual Vector for Gauss-Seidel

We would like the residual vectors to converge as rapidly as possible to the zero vector. Let the approximate solution vector to the Gauss-Seidel method be expressed as

$$\mathbf{x}_i^{(k)} = \begin{bmatrix} x_1^{(k)} \\ x_2^{(k)} \\ \vdots \\ x_{i-1}^{(k)} \\ x_i^{(k-1)} \\ \vdots \\ x_n^{(k-1)} \end{bmatrix}$$

Express the residual vector $\mathbf{r} = \mathbf{b} - A\tilde{\mathbf{x}}$.

$$\mathbf{r}_i^{(k)} = \mathbf{b} - A\mathbf{x}_i^{(k)}$$

$$\begin{bmatrix} r_{1i}^{(k)} \\ r_{2i}^{(k)} \\ \vdots \\ r_{mi}^{(k)} \\ \vdots \\ r_{ni}^{(k)} \end{bmatrix} = \begin{bmatrix} b_1 \\ b_2 \\ \vdots \\ b_m \\ \vdots \\ b_n \end{bmatrix} - \begin{bmatrix} a_{11} & a_{12} & \cdots & a_{1n} \\ a_{21} & a_{22} & \cdots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{m1} & a_{m2} & \cdots & a_{mn} \\ \vdots & \vdots & \ddots & \vdots \\ a_{n1} & a_{n2} & \cdots & a_{nn} \end{bmatrix} \begin{bmatrix} x_1^{(k)} \\ x_2^{(k)} \\ \vdots \\ x_{i-1}^{(k)} \\ x_i^{(k-1)} \\ \vdots \\ x_n^{(k-1)} \end{bmatrix}$$

$$\mathbf{r}_i^{(k)} = \mathbf{b} - A\mathbf{x}_i^{(k)}$$

$$\begin{bmatrix} r_{1i}^{(k)} \\ r_{2i}^{(k)} \\ \vdots \\ r_{mi}^{(k)} \\ \vdots \\ r_{ni}^{(k)} \end{bmatrix} = \begin{bmatrix} b_1 \\ b_2 \\ \vdots \\ b_m \\ \vdots \\ b_n \end{bmatrix} - \begin{bmatrix} a_{11} & a_{12} & \cdots & a_{1n} \\ a_{21} & a_{22} & \cdots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{m1} & a_{m2} & \cdots & a_{mn} \\ \vdots & \vdots & \ddots & \vdots \\ a_{n1} & a_{n2} & \cdots & a_{nn} \end{bmatrix} \begin{bmatrix} x_1^{(k)} \\ x_2^{(k)} \\ \vdots \\ x_{i-1}^{(k)} \\ x_i^{(k-1)} \\ \vdots \\ x_n^{(k-1)} \end{bmatrix}$$

Note: for $1 \leq m \leq n$

$$r_{mi}^{(k)} = b_m - \sum_{j=1}^{i-1} a_{mj} x_j^{(k)} - \sum_{j=i}^n a_{mj} x_j^{(k-1)}.$$

$$\begin{aligned}
 r_{mi}^{(k)} &= b_m - \sum_{j=1}^{i-1} a_{mj} x_j^{(k)} - \sum_{j=i}^n a_{mj} x_j^{(k-1)} \\
 &= b_m - \sum_{j=1}^{i-1} a_{mj} x_j^{(k)} - a_{mi} x_i^{(k-1)} - \sum_{j=i+1}^n a_{mj} x_j^{(k-1)}
 \end{aligned}$$

$$\begin{aligned}
 r_{mi}^{(k)} &= b_m - \sum_{j=1}^{i-1} a_{mj} x_j^{(k)} - \sum_{j=i}^n a_{mj} x_j^{(k-1)} \\
 &= b_m - \sum_{j=1}^{i-1} a_{mj} x_j^{(k)} - a_{mi} x_i^{(k-1)} - \sum_{j=i+1}^n a_{mj} x_j^{(k-1)}
 \end{aligned}$$

$$r_{ii}^{(k)} = b_i - \sum_{j=1}^{i-1} a_{ij} x_j^{(k)} - a_{ii} x_i^{(k-1)} - \sum_{j=i+1}^n a_{ij} x_j^{(k-1)}$$

$$a_{ii} x_i^{(k-1)} + r_{ii}^{(k)} = b_i - \sum_{j=1}^{i-1} a_{ij} x_j^{(k)} - \sum_{j=i+1}^n a_{ij} x_j^{(k-1)}$$

$$\begin{aligned}
 r_{mi}^{(k)} &= b_m - \sum_{j=1}^{i-1} a_{mj} x_j^{(k)} - \sum_{j=i}^n a_{mj} x_j^{(k-1)} \\
 &= b_m - \sum_{j=1}^{i-1} a_{mj} x_j^{(k)} - a_{mi} x_i^{(k-1)} - \sum_{j=i+1}^n a_{mj} x_j^{(k-1)}
 \end{aligned}$$

$$r_{ii}^{(k)} = b_i - \sum_{j=1}^{i-1} a_{ij} x_j^{(k)} - a_{ii} x_i^{(k-1)} - \sum_{j=i+1}^n a_{ij} x_j^{(k-1)}$$

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$$a_{ii} x_i^{(k-1)} + r_{ii}^{(k)} = a_{ii} x_i^{(k)} \quad (\text{for Gauss-Seidel method})$$

$$x_i^{(k)} = x_i^{(k-1)} + \frac{r_{ii}^{(k)}}{a_{ii}}$$

Thus the Gauss-Seidel method can be thought of as choosing $x_i^{(k)}$ such that

$$x_i^{(k)} = x_i^{(k-1)} + \frac{r_{ii}^{(k)}}{a_{ii}}.$$

Now consider the residual vector $\mathbf{r}_{i+1}^{(k)}$ associated with the approximate solution

$$\mathbf{x}_{i+1}^{(k)} = \begin{bmatrix} x_1^{(k)} \\ x_2^{(k)} \\ \vdots \\ x_i^{(k)} \\ x_{i+1}^{(k-1)} \\ \vdots \\ x_n^{(k-1)} \end{bmatrix}.$$

$$\mathbf{r}_{i+1}^{(k)} = \mathbf{b} - A\mathbf{x}_{i+1}^{(k)}$$

$$\begin{bmatrix} r_{1,i+1}^{(k)} \\ r_{2,i+1}^{(k)} \\ \vdots \\ r_{m,i+1}^{(k)} \\ \vdots \\ r_{n,i+1}^{(k)} \end{bmatrix} = \begin{bmatrix} b_1 \\ b_2 \\ \vdots \\ b_m \\ \vdots \\ b_n \end{bmatrix} - \begin{bmatrix} a_{11} & a_{12} & \cdots & a_{1n} \\ a_{21} & a_{22} & \cdots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{m1} & a_{m2} & \cdots & a_{mn} \\ \vdots & \vdots & \ddots & \vdots \\ a_{n1} & a_{n2} & \cdots & a_{nn} \end{bmatrix} \begin{bmatrix} x_1^{(k)} \\ x_2^{(k)} \\ \vdots \\ x_i^{(k)} \\ x_{i+1}^{(k-1)} \\ \vdots \\ x_n^{(k-1)} \end{bmatrix}$$

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Note: for $1 \leq m \leq n$

$$r_{m,i+1}^{(k)} = b_m - \sum_{j=1}^i a_{mj} x_j^{(k)} - \sum_{j=i+1}^n a_{mj} x_j^{(k-1)}.$$

$$\begin{aligned}
 r_{m,i+1}^{(k)} &= b_m - \sum_{j=1}^i a_{mj} x_j^{(k)} - \sum_{j=i+1}^n a_{mj} x_j^{(k-1)} \\
 &= b_m - \sum_{j=1}^{i-1} a_{mj} x_j^{(k)} - a_{mi} x_i^{(k)} - \sum_{j=i+1}^n a_{mj} x_j^{(k-1)}
 \end{aligned}$$

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 \end{aligned}$$

$$\begin{aligned}
 r_{i,i+1}^{(k)} &= b_i - \sum_{j=1}^{i-1} a_{ij} x_j^{(k)} - \sum_{j=i+1}^n a_{ij} x_j^{(k-1)} - a_{ii} x_i^{(k)} \\
 &= 0 \text{ (for Gauss-Seidel method)}
 \end{aligned}$$

The Gauss-Seidel method chooses $x_{i+1}^{(k)}$ so that $r_{i,i+1}^{(k)} = 0$.

Reducing the Norm of the Residual Vector

We make the following modification to the earlier equation:

$$x_i^{(k)} = x_i^{(k-1)} + \frac{r_{ii}^{(k)}}{a_{ii}}$$

in order to reduce the norm of the residual vector most efficiently. Let

$$x_i^{(k)} = x_i^{(k-1)} + \omega \frac{r_{ii}^{(k)}}{a_{ii}}$$

where $\omega > 0$.

Such a method is called a **relaxation method**.

- ▶ For $0 < \omega < 1$ these are called **under-relaxation methods**.
- ▶ For $1 < \omega$ these are called **over-relaxation methods**.

Successive Over-Relaxation (SOR)

Let $1 < \omega$, then

$$\begin{aligned}x_i^{(k)} &= x_i^{(k-1)} + \omega \frac{r_{ii}^{(k)}}{a_{ii}} \\&= x_i^{(k-1)} + \frac{\omega}{a_{ii}} \left[b_i - \sum_{j=1}^{i-1} a_{ij} x_j^{(k)} - a_{ii} x_i^{(k-1)} - \sum_{j=i+1}^n a_{ij} x_j^{(k-1)} \right] \\&= (1 - \omega) x_i^{(k-1)} + \frac{\omega}{a_{ii}} \left[b_i - \sum_{j=1}^{i-1} a_{ij} x_j^{(k)} - \sum_{j=i+1}^n a_{ij} x_j^{(k-1)} \right]\end{aligned}$$

Matrix Formulation

The equation

$$x_i^{(k)} = (1 - \omega)x_i^{(k-1)} + \frac{\omega}{a_{ii}} \left[b_i - \sum_{j=1}^{i-1} a_{ij}x_j^{(k)} - \sum_{j=i+1}^n a_{ij}x_j^{(k-1)} \right]$$

is equivalent to

$$a_{ii}x_i^{(k)} + \omega \sum_{j=1}^{i-1} a_{ij}x_j^{(k)} = (1 - \omega)a_{ii}x_i^{(k-1)} - \omega \sum_{j=i+1}^n a_{ij}x_j^{(k-1)} + \omega b_i$$

Matrix Formulation

The equation

$$x_i^{(k)} = (1 - \omega)x_i^{(k-1)} + \frac{\omega}{a_{ii}} \left[b_i - \sum_{j=1}^{i-1} a_{ij}x_j^{(k)} - \sum_{j=i+1}^n a_{ij}x_j^{(k-1)} \right]$$

is equivalent to

$$\begin{aligned} a_{ii}x_i^{(k)} + \omega \sum_{j=1}^{i-1} a_{ij}x_j^{(k)} &= (1 - \omega)a_{ii}x_i^{(k-1)} - \omega \sum_{j=i+1}^n a_{ij}x_j^{(k-1)} + \omega b_i \\ (D - \omega L)\mathbf{x}^{(k)} &= [(1 - \omega)D + \omega U]\mathbf{x}^{(k-1)} + \omega \mathbf{b} \\ \mathbf{x}^{(k)} &= (D - \omega L)^{-1} [(1 - \omega)D + \omega U]\mathbf{x}^{(k-1)} + \omega(D - \omega L)^{-1}\mathbf{b} \end{aligned}$$

Matrix Formulation

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$$x_i^{(k)} = (1 - \omega)x_i^{(k-1)} + \frac{\omega}{a_{ii}} \left[b_i - \sum_{j=1}^{i-1} a_{ij}x_j^{(k)} - \sum_{j=i+1}^n a_{ij}x_j^{(k-1)} \right]$$

is equivalent to

$$\begin{aligned} a_{ii}x_i^{(k)} + \omega \sum_{j=1}^{i-1} a_{ij}x_j^{(k)} &= (1 - \omega)a_{ii}x_i^{(k-1)} - \omega \sum_{j=i+1}^n a_{ij}x_j^{(k-1)} + \omega b_i \\ (D - \omega L)\mathbf{x}^{(k)} &= [(1 - \omega)D + \omega U]\mathbf{x}^{(k-1)} + \omega \mathbf{b} \\ \mathbf{x}^{(k)} &= (D - \omega L)^{-1} [(1 - \omega)D + \omega U]\mathbf{x}^{(k-1)} + \omega (D - \omega L)^{-1} \mathbf{b} \\ \mathbf{x}^{(k)} &= T_\omega \mathbf{x}^{(k-1)} + \mathbf{c}_\omega \end{aligned}$$

Example

Compare the Gauss-Seidel iterative method to the SOR method with $\omega = 1.25$ for solving the following linear system. Use $\mathbf{x}^{(0)} = \mathbf{0}$ and let $\epsilon = 10^{-3}$.

$$\begin{aligned} -2x_1 + x_2 + \frac{1}{2}x_3 &= 4 \\ x_1 - 2x_2 - \frac{1}{2}x_3 &= -4 \\ x_2 + 2x_3 &= 0 \end{aligned}$$

The exact solution is

$$\begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} -16/11 \\ 16/11 \\ -8/11 \end{bmatrix} \approx \begin{bmatrix} -1.454545 \\ 1.454545 \\ -0.727273 \end{bmatrix}.$$

Solution (1 of 5)

The Gauss-Seidel method can be expressed in matrix form as

$$\mathbf{x}^{(k)} = T_g \mathbf{x}^{(k-1)} + \mathbf{c}_g = \begin{bmatrix} 0 & 1/2 & 1/4 \\ 0 & 1/4 & -1/8 \\ 0 & -1/8 & 1/16 \end{bmatrix} \begin{bmatrix} x_1^{(k-1)} \\ x_2^{(k-1)} \\ x_3^{(k-1)} \end{bmatrix} + \begin{bmatrix} -2 \\ 1 \\ -1/2 \end{bmatrix}.$$

Solution (2 of 5)

With $\omega = 1.25$ then

$$D - \omega L = \begin{bmatrix} -2 & 0 & 0 \\ 0 & -2 & 0 \\ 0 & 0 & 2 \end{bmatrix} - \frac{5}{4} \begin{bmatrix} 0 & 0 & 0 \\ -1 & 0 & 0 \\ 0 & -1 & 0 \end{bmatrix} = \begin{bmatrix} -2 & 0 & 0 \\ 5/4 & -2 & 0 \\ 0 & 5/4 & 2 \end{bmatrix}$$

$$(D - \omega L)^{-1} = \begin{bmatrix} -1/2 & 0 & 0 \\ -5/16 & -1/2 & 0 \\ 25/128 & 5/16 & 1/2 \end{bmatrix}$$

$$\begin{aligned} (1 - \omega)D + \omega U &= \frac{-1}{4} \begin{bmatrix} -2 & 0 & 0 \\ 0 & -2 & 0 \\ 0 & 0 & 2 \end{bmatrix} + \frac{5}{4} \begin{bmatrix} 0 & -1 & -1/2 \\ 0 & 0 & 1/2 \\ 0 & 0 & 0 \end{bmatrix} \\ &= \begin{bmatrix} 1/2 & -5/4 & -5/8 \\ 0 & 1/2 & 5/8 \\ 0 & 0 & -1/2 \end{bmatrix} \end{aligned}$$

Solution (3 of 5)

$$\begin{aligned}T_{\omega} &= (D - \omega L)^{-1} [(1 - \omega)D + \omega U] \\&= \begin{bmatrix} -1/2 & 0 & 0 \\ -5/16 & -1/2 & 0 \\ 25/128 & 5/16 & 1/2 \end{bmatrix} \begin{bmatrix} 1/2 & -5/4 & -5/8 \\ 0 & 1/2 & 5/8 \\ 0 & 0 & -1/2 \end{bmatrix} \\&= \frac{1}{1024} \begin{bmatrix} -256 & 640 & 320 \\ -160 & 144 & -120 \\ 100 & -90 & -181 \end{bmatrix} \\ \mathbf{c}_{\omega} &= \omega(D - \omega L)^{-1} \mathbf{b} \\&= \frac{5}{4} \begin{bmatrix} -1/2 & 0 & 0 \\ -5/16 & -1/2 & 0 \\ 25/128 & 5/16 & 1/2 \end{bmatrix} \begin{bmatrix} 4 \\ -4 \\ 0 \end{bmatrix} \\&= \frac{1}{128} \begin{bmatrix} -320 \\ 120 \\ -75 \end{bmatrix}\end{aligned}$$

Solution (4 of 5)

The SOR method (with $\omega = 1.25$) can be expressed in matrix form as

$$\mathbf{x}^{(k)} = T_{\omega} \mathbf{x}^{(k-1)} + \mathbf{c}_{\omega} = \frac{1}{1024} \begin{bmatrix} -256 & 640 & 320 \\ -160 & 144 & -120 \\ 100 & -90 & -181 \end{bmatrix} \begin{bmatrix} x_1^{(k-1)} \\ x_2^{(k-1)} \\ x_3^{(k-1)} \end{bmatrix} + \frac{1}{128} \begin{bmatrix} -320 \\ 120 \\ -75 \end{bmatrix}$$

Solution (5 of 5)

k	Gauss-Seidel			SOR ($\omega = 1.25$)		
	$x_1^{(k)}$	$x_2^{(k)}$	$x_3^{(k)}$	$x_1^{(k)}$	$x_2^{(k)}$	$x_3^{(k)}$
0	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000
1	-2.0000	1.0000	-0.5000	-2.5000	0.9375	-0.5859
2	-1.6250	1.3125	-0.6523	-1.4722	1.5286	-0.8089
3	-1.5078	1.4102	-0.7051	-1.4294	1.4773	-0.7211
4	-1.4712	1.4407	-0.7203	-1.4447	1.4531	-0.7279
5	-1.4598	1.4502	-0.7251	-1.4581	1.4529	-0.7261
6	-1.4562	1.4532	-0.7266	-1.4543	1.4547	-0.7277
7	-1.4551	1.4541	-0.7271	-1.4546	1.4546	-0.7272

Choosing ω Optimally

Comment: there is no known method for choosing the best value of ω for the general $n \times n$ matrix A . For some commonly occurring special cases the optimal ω can be calculated.

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Theorem (Kahan)

If $a_{ii} \neq 0$ for $i = 1, 2, \dots, n$ then $\rho(T_\omega) \geq |\omega - 1|$. Thus the SOR method can converge only if $0 < \omega < 2$.

Positive Definite A

Theorem (Ostrowski-Reich)

If A is a positive definite matrix and $0 < \omega < 2$ then the SOR method will converge for any choice of initial approximation vector $\mathbf{x}^{(0)}$.

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If A is a positive definite matrix and $0 < \omega < 2$ then the SOR method will converge for any choice of initial approximation vector $\mathbf{x}^{(0)}$.

Theorem

If A is positive definite and tridiagonal, then $\rho(T_g) = [\rho(T_j)]^2 < 1$ and the optimal choice of ω for the SOR method is

$$\omega = \frac{2}{1 + \sqrt{1 - [\rho(T_j)]^2}}.$$

For this choice of ω , then $\rho(T_\omega) = \omega - 1$.

Example

Find the optimal choice of ω for solving the following linear system.

$$\begin{aligned}4x_1 + x_2 - x_3 &= 5 \\ -x_1 + 3x_2 + x_3 &= -4 \\ 2x_1 + 2x_2 + 5x_3 &= 1\end{aligned}$$

The exact solution is

$$\begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 97/67 \\ -56/67 \\ -3/67 \end{bmatrix} \approx \begin{bmatrix} 1.447761 \\ -0.835821 \\ -0.044776 \end{bmatrix}.$$

Solution (1 of 4)

In this positive definite, tridiagonal system

$$A = \begin{bmatrix} 4 & 1 & -1 \\ -1 & 3 & 1 \\ 2 & 2 & 5 \end{bmatrix}$$

$$D = \begin{bmatrix} 4 & 0 & 0 \\ 0 & 3 & 0 \\ 0 & 0 & 5 \end{bmatrix}$$

$$L = \begin{bmatrix} 0 & 0 & 0 \\ 1 & 0 & 0 \\ -2 & -2 & 0 \end{bmatrix}$$

$$U = \begin{bmatrix} 0 & -1 & 1 \\ 0 & 0 & -1 \\ 0 & 0 & 0 \end{bmatrix}.$$

Solution (2 of 4)

$$\begin{aligned}T_j &= D^{-1}(L + U) = \begin{bmatrix} 1/4 & 0 & 0 \\ 0 & 1/3 & 0 \\ 0 & 0 & 1/5 \end{bmatrix} \begin{bmatrix} 0 & -1 & 1 \\ 1 & 0 & -1 \\ -2 & -2 & 0 \end{bmatrix} \\&= \begin{bmatrix} 0 & -1/4 & 1/4 \\ 1/3 & 0 & -1/3 \\ -2/5 & -2/5 & 0 \end{bmatrix}\end{aligned}$$

The eigenvalues of T_j are

$$\begin{aligned}\lambda_1 &\approx 0.182266 + 0.386862i \\ \lambda_2 &\approx 0.182266 - 0.386862i \\ \lambda_3 &\approx -0.364531.\end{aligned}$$

The magnitudes of the eigenvalues of T_j are

$$\begin{aligned}|\lambda_1| &\approx \sqrt{(0.182266)^2 + (0.386862)^2} \approx 0.427648 \\ |\lambda_2| &\approx \sqrt{(0.182266)^2 + (-0.386862)^2} \approx 0.427648 \\ |\lambda_3| &\approx |0.364531|.\end{aligned}$$

The spectral radius of T_j is $\rho(T_j) \approx 0.427648$.

Solution (3 of 4)

The optimal choice of ω for SOR is

$$\omega = \frac{2}{1 + \sqrt{1 - [\rho(T_j)]^2}} \approx \frac{2}{1 + \sqrt{1 - (0.427648)^2}} = 1.05045.$$

Solution (3 of 4)

The optimal choice of ω for SOR is

$$\omega = \frac{2}{1 + \sqrt{1 - [\rho(T_j)]^2}} \approx \frac{2}{1 + \sqrt{1 - (0.427648)^2}} = 1.05045.$$

The SOR method for solving this linear system then takes the form:

$$\begin{aligned} \mathbf{x}^{(k)} &= T_\omega \mathbf{x}^{(k-1)} + \mathbf{c}_\omega \\ \begin{bmatrix} x_1^{(k)} \\ x_3^{(k)} \\ x_3^{(k)} \end{bmatrix} &\approx \begin{bmatrix} -0.0504504 & -0.262613 & 0.262613 \\ -0.0176652 & -0.142404 & -0.258196 \\ 0.0286208 & 0.17018 & -0.0523061 \end{bmatrix} \begin{bmatrix} x_1^{(k-1)} \\ x_3^{(k-1)} \\ x_3^{(k-1)} \end{bmatrix} \\ &\quad + \begin{bmatrix} 1.31306 \\ -0.940831 \\ 0.0536857 \end{bmatrix} \end{aligned}$$

Solution (4 of 4)

k	$x_1^{(k)}$	$x_2^{(k)}$	$x_3^{(k)}$
0	0.0000	0.0000	0.0000
1	1.31306	-0.940831	0.0536857
2	1.50799	-0.84391	-0.0716521
3	1.43979	-0.828794	-0.0430231
4	1.44678	-0.837133	-0.0439001
5	1.44839	-0.835843	-0.0450734
6	1.44766	-0.835752	-0.0447464
7	1.44776	-0.835837	-0.0447689
8	1.44777	-0.83582	-0.0447793
9	1.44776	-0.83582	-0.0447757
10	1.44776	-0.835821	-0.0447761

Homework

- ▶ Read Section 7.4.
- ▶ Exercises: 1ac, 3ac, 7ac, 13